



鸿汇精密®





## Shenzhen Homwing Technology Co.,Ltd.

Add: E, 3/F, Building 1, Xinyuan Industrial Zone, Shangwei Park, Guxing Community, Xixiang Street, Bao'an District, 518126 Shenzhen, China

Tel: (+86) 0755-237 14105 Fax: (+86) 0755-2371 4105 E-mail: xs@homwing.com



en.homwing.com

To manufacture the most competitive execution parts in an intelligent manner for industry automation

The scale and strength of the transmission components supplier, committed to build an excellent Chinese transmission brand

## Company Vision

To establish itself as "a professional supplier of precision harmonic drives & electric clamping jaws with independent intellectual property rights and well-known brands"

## Company Purpose

Bringing together talent, market-focused technological innovation

## Company Values

We integrate consistent sentiment with our business, and through the team, encourage flexibility and innovation to achieve common goals——Build an aircraft carrier-class company!

## Company Mission

Satisfy customers Successfully fulfill commitments Interdependence with customers Respect individuals, serve customers, and strive for

# CONTENTS

Company Introduction ————————————————————————————————————	01
Technology/Product Advantages	03
Full Range of Products	05
HEPG Series Modular Electric Gripper	07
HEPG-HP Series Modular Electric Gripper	15
HEPG-M Series Mini Electric Parallel Gripper	17
HEPG-L Series Long Stroke Electric Parallel Gripper	19
HLEPG Series Lithium Battery Electric Parallel Gripper	21
HERG Series Modular Electric Gripper	23
IHERG Series Lightweight Electric Rotary Gripper	27
HRG Series Robot Electric Gripper	30
HRCG Series Rotary Radial Gripper	33
HEVS Series Electric Vacuum Actuator	35
HLRA Linear Rotary Actuator	38
Torque Diagram —————	40
Product Application Example —	41
Our Services —	42

## COMPANY INTRODUCTION

Shenzhen Homwing Technology Co.,Ltd., founded in 2014, is located in Shenzhen, the prosperous economic capital of China, and is committed to the research and development of high-precision transmission components. It is a high-tech enterprise integrating R & D, design, production and sales. The company has strong technical force, complete testing means and high standard quality management system. All links from raw materials to finished products are strictly supervised and controlled. It provides a solid foundation for product quality. Our products are sold all over the country and abroad.

The harmonic reducer ,electric gripper and other high-precision transmission components independently developed by the company. Under the premise of quality assurance, after being promoted to the market at discounted prices, it has been widely used and recognized by many mainstream industrial robot manufacturers both domestically and internationally, it has been used and affirmed by many mainstream industrial robot manufacturers at home and abroad. In recent years, it has made remarkable achievements in industry robots, metal machine tools, medical devices, laser processing, cutting, dispensing, printing, LED equipment manufacturing, precision electronic equipment and automation industries.

Homwing will always adhere to the purpose of "gathering talents, close to the market and technological innovation", seek the common development of the company and society, and quietly build itself into a "excellent Chinese transmission brand".

2014 **Established Time** 

300+ **Cooperative customers** 

50+ **Production staff** 

The harmonic reducer ,intelligent electric transla tional gripper and other high-precision transmission components independently developed by the company.



## **TECHNOLOGY PRODUCT ADVANTAGES**



#### **HEPG Series Modular Electric Gripper**



#### HEPG26-006

Weight: 0.40kg

IP Grade: IP40, IP 65 Optional

Adjustable Stroke:0-26mm Clamping Force:1-6N Weight: 0.20kg IP Grade:IP40



#### **HEPG26-015**

Adjustable Stroke:0-26mm Clamping Force:1-15N Weight: 0.25kg IP Grade:IP40



#### **HEPG40-100**

Adjustable Stroke:0-40mm Clamping Force:40-100N Weight: 0.44kg IP Grade:IP40



#### **HEPG50-100**

Adjustable Stroke:0-50mm Clamping Force:40-100N Weight:0.53kg IP Grade:IP40



## **HEPG80-140**

Adjustable Stroke :0-80mm Clamping Force:50-150N Weight:1.5Kg IP Grade :IP40

#### **HEPG-HP Series Modular Electric Gripper**



### **HEPG-HP26-050**

Adjustable Stroke: 0-26mm Clamping Force: 5-50N Weight: 0.45kg IP Grade: IP40



HEPG-M Series Mini Electric Parallel Gripper

### **HEPG-M06-015**

Stroke:6mm Clamping Force: 6/15N Two-gear adjustable Weight: 0.20kg IP Grade: IP20

#### **HEPG-L Series Long Stroke Electric Parallel Gripper**

**HLEPG Series Lithium Battery Electric Parallel Gripper** 



#### **HEPG-L180-350**

Adjustable Stroke:180mm Clamping Force:100-350N Weight:3kg IIP Grade:IP40



#### **HLEPG70-500**

Adjustable Stroke:0-70mm Clamping Force:40-500N Maximum Load: 10 kg Weight:3kg IP Grade: IP43

#### **HERG Series Electric Rotary Gripper**



#### HERG08-023

Adjustable Stroke:0-8mm Clamping Force:4-23N Weight: 0.60kg Peak torque:0.3N·m Rotational speed:1500°/s Opening/and closing time:0.2s IP Grade: IP40



#### HERG32-150

Adjustable stroke: 0-32mm Clamping force: 40-100N Weight: 0.65kg Peak torque: 1N·m Rotational speed: 1500°/s IP grade: IP40



#### HERG32-150T

Adjustable stroke: 0-32mm Clamping force: 40-100N Weight: 0.70kg Peak torque: 1.5N·m Rotational speed: 1000°/s IP grade: IP40

#### **IHERG Series Lightweight Electric Rotary Gripper**



#### **IHERG08-015**

Adjustable stroke :0-8mm Clamping force:10-15N Weight:0.30kg Rotational speed:1500°/s IP grade:IP40



#### IHERG16-030

Adjustable stroke:16mm Clamping force :40-70N Weight: 0.31kg Recommended Maximum load: 0.2kg IP grade:IP40

#### **HRG Series Robot Electric Gripper**



#### HRG75-300

Adjustable Stroke:0-52 mm Clamping Force: 2-50 N Maximum Recommended Load:1 kg Weight: 0.75 Kg IP Grade:IP54



#### HRG75-300

Adjustable Stroke:0-75 mm Clamping Force:40-300 N Maximum Recommended Load:6 Kg Weight: 1.5 Kg IP Grade:IP65

#### **HRCG Series Rotary Radial Gripper**



#### HRCG90-065

Adjustable Stroke:65N Clamping Force:90mm Maximum Recommended Load: 2 kg Weight:1Kg IP Grade:IP40



## HEVS01

Suction/release time: suction: 0.10s/release: 0.10s Recommended Maximum load:1kg Maximum Vacuum Degree:60% Weight:0.3kg IP Grade:IP40

#### **HLRA Linear Rotary Actuator**



#### **HLRA**

Rated thrust:10N Rated Torque:0.01 N⋅m Maximum speed:1000 rpm IP Grade:IP40



#### HEVS08

Suction/release time: suction: 0.40s/release: 0.20s Maximum load: 4kg (load) 8kg (chassis extension) Maximum vacuum degree: 70% Weight: 1.4kg

Protection level: IP54

## HEPG

## **MODULAR ELECTRIC GRIPPER**

Installable On Four Sides **Networking Application** Ultra-large Stroke Precise Force Control

\*Fingers Need To Be Optional











Precision Manufacturing



Medical



**Education** 

## **PRODUCT ADVANTAGES**



Ultra-large

Stroke















Drop

Detection







Voltage

024



## **MODEL SELECTION**

Product Stroke Series

**HEPG** 

40

Clamping

Force

050

0

Wiring

Position

L#

Cable Fixed-end

Length

0-side Wiring L#-default 200mm 1-bottom Wiring L5000-5000mm C1-485+I/0 (NN)

C0-485 024-24V C2-485+I/0 (PP)

Communication Power

Mode

CO

C3-485+I/0 (NP) C4-485+I/0 (PN)

Grade

A-default B-first Upgrade C-secondary Upgrade

Model Version

( Customer Configuration )

## **HEPG**

## HEPG26-006-1L#-C0024-P40-A

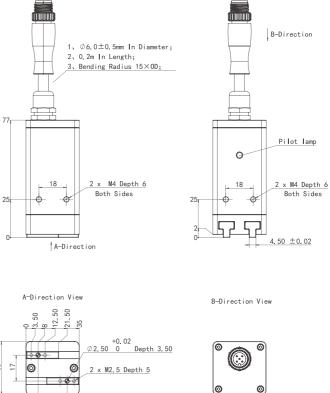
## **PRODUCT PARAMETERS**

Adjustable Stroke	0-26 mm	Rated Voltage	DC 24±10% V
Clamping Force of One Finger	1-6 N	Maximum Current	0.85 A
Opening/Closing Time	0.25s	Rated Current	0.4 A
Positional Repeatability	±0.02 mm	Communication Protocol	Modbus RTU(RS 485)
*Maximum Recommended Load	0.1 Kg	International Standards Met	CE、RoHS
Drop Detection	Supported	Allowable Static Load in Vertical Direction Fz	100 N
Applicable Environment	5~40℃, 85% RH below	Allowable Static Torque Of The Slider Mx	0.8 N·m
Operating Noise	< 40 dB	Allowable Static Torque Of The Slider My	0.6 N·m
Weight	0.20 Kg	Allowable Static Torque Of The Slider Mz	0.5 N·m
IP Grade	IP40		



<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**





## **HEPG**

## HEPG26-015-1L#-C0024-P40-A

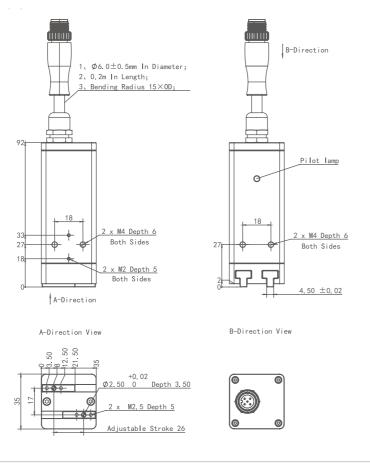


## **PRODUCT PARAMETERS**

Adjustable Stroke	0-26 mm	Rated Voltage	DC 24±10% V	
Clamping Force of One Finger	1-15 N	Maximum Current	0.85 A	
Opening/Closing Time	0.3s	Rated Current	0.4 A	
Positional Repeatability	±0.02 mm	Communication Protocol	Modbus RTU(RS 485)	
*Maximum Recommended Load	0.3 Kg	International Standards Met	CE、RoHS	
Drop Detection	Supported	Allowable Static Load in Vertical Direction Fz	150 N	
Applicable Environment	5~40℃, 85% RH below	Allowable Static Torque Of The Slider Mx	1.2 N·m	
Operating Noise	< 40 dB	Allowable Static Torque Of The Slider My	0.9 N·m	
Weight	0.25 Kg	Allowable Static Torque Of The Slider Mz	0.55 N·m	
IP Grade	IP40			

<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**



## **HEPG** HEPG40-050-0L#-C0024-P40-A

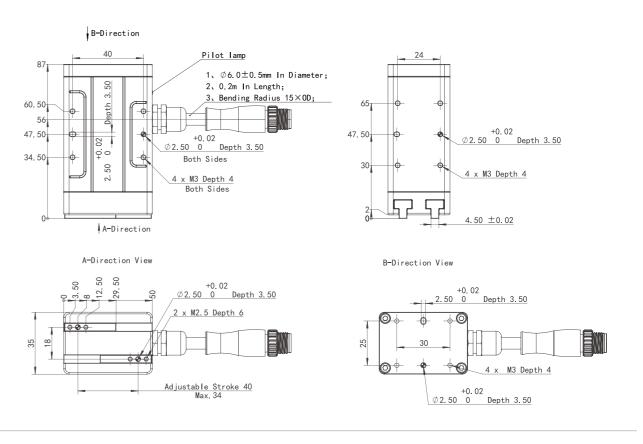
## **PRODUCT PARAMETERS**

Adjustable Stroke	0-40 mm	Rated Voltage	DC 24±10% V
Clamping Force of One Finger	2-50 N	Maximum Current	0.85 A
Opening/Closing Time	0.5s	Rated Current	0.4 A
Positional Repeatability	±0.02 mm		Modbus RTU(RS 485)
*Maximum Recommended Load	0.8 Kg	Communication Protocol	Digital I/O optional
Drop Detection	Supported	International Standards Met	CE、RoHS
Applicable Environment	5~40℃, 85% RH below	Allowable Static Load in Vertical Direction Fz	200 N
Operating Noise	< 40 dB	Allowable Static Torque Of The Slider Mx	2 N·m
Weight	0.36 Kg	Allowable Static Torque Of The Slider My	1.5 N·m
IP Grade	IP40、IP65 optional	Allowable Static Torque Of The Slider Mz	2 N·m



<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**



# HEPG40-100-0L#-C0024-P40-A

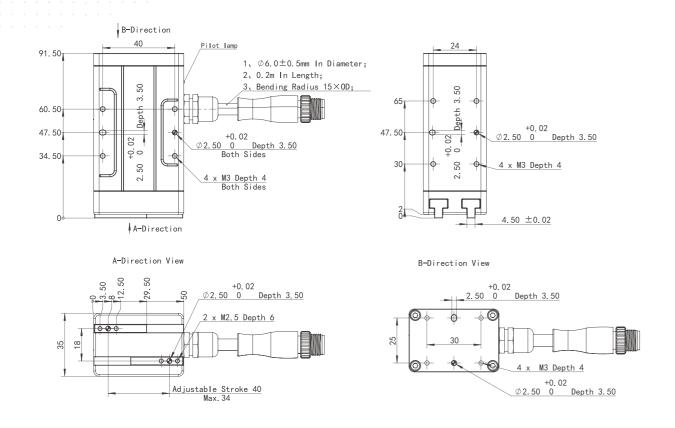
# (E) Hamwing

## **PRODUCT PARAMETERS**

Adjustable Stroke	0-40 mm	Rated Voltage	DC 24±10% V	
Clamping Force of One Finger	40-100 N	Maximum Current	0.85 A	
Opening/Closing Time	0.9s	Rated Current	0.4 A	
Positional Repeatability	±0.02 mm		Modbus RTU(RS 485)	
*Maximum Recommended Load	2 Kg	Communication Protocol	Digital I/O optiona	
Drop Detection	Supported	International Standards Met	CE、RoHS	
Applicable Environment	5~40°C, 85% RH below	Allowable Static Load in Vertical Direction Fz	200 N	
Operating Noise	< 40 dB	Allowable Static Torque of The Slider Mx	2 N·m	
Weight	0.37 Kg	Allowable Static Torque of The Slider My	1.5 N·m	
IP Grade	IP40、IP65 optional	Allowable Static Torque of The Slider Mz	2 N·m	

\*It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**



# **HEPG**50-060-0L#-C0024-P40-A

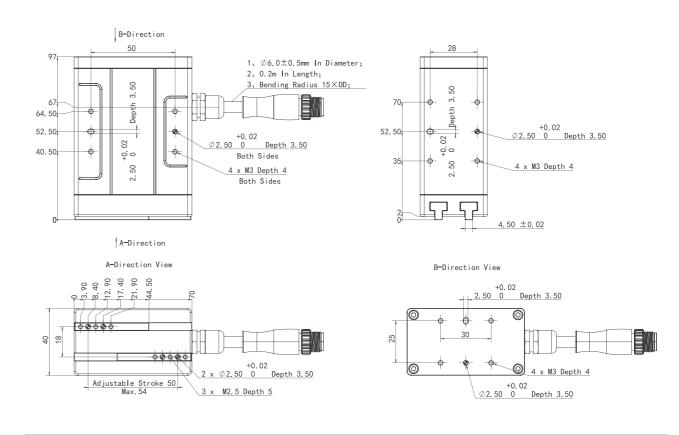
## **PRODUCT PARAMETERS**

Adjustable Stroke	0-50 mm	Rated Voltage	DC 24±10% V
Clamping Force of One Finger	2-60 N	Maximum Current	0.85 A
Opening/Closing Time	0.6s	Rated Current	0.4 A
Positional Repeatability	±0.02 mm		Modbus RTU(RS 485)
*Maximum Recommended Load	1 Kg	Communication Protocol	Digital I/O optional
Support Drop Detection or Not	Supported	International Standards Met	CE、RoHS
Applicable Environment	5~40℃, 85% RH below	Allowable Static Load in Vertical Direction Fz	200 N
Operating Noise	< 40 dB	Allowable Static Torque of The Slider Mx	2 N·m
Weight	0.57 Kg	Allowable Static Torque of The Slider My	1.5 N·m
IP Grade	IP40、IP65 optional	Allowable Static Torque of The Slider Mz	2 N·m



<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**



# HEPG50-100-0L#-C0024-P40-A

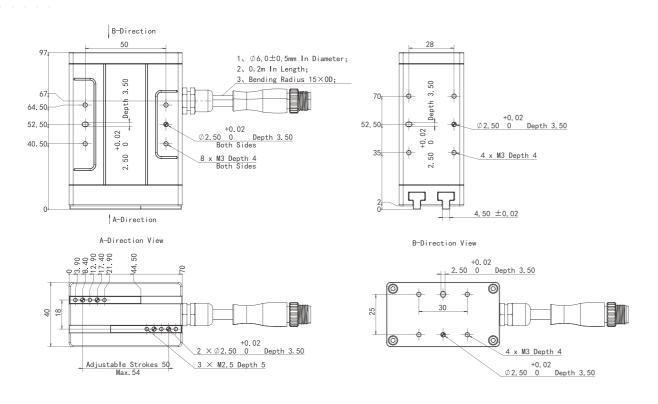


## **PRODUCT PARAMETERS**

Adjustable Stroke	0-50 mm	Rated Voltage	DC 24±10% V
Clamping Force of One Finger	40-100 N	Maximum Current	0.6 A
Opening/Closing Time	1.10s	Rated Current	0.25 A
Positional Repeatability	±0.02 mm		Modbus RTU(RS 485)
*Maximum Recommended Load	2 Kg	Communication Protocol	Digital I/O optional
Support Drop Detection or Not	Supported	International Standards Met	CE、RoHS
Applicable Environment	5~40℃, 85% RH below	Allowable Static Load in Vertical Direction Fz	200 N
Operating Noise	< 40 dB	Allowable Static Torque of The Slider Mx	2.5 N·m
Weight	0.53 Kg	Allowable Static Torque of The Slider My	2 N·m
IP Grade	IP40、IP65 optional	Allowable Static Torque of The Slider Mz	2.8 N·m

<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

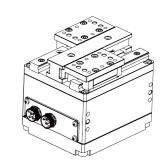
## **DIMENSIONS**



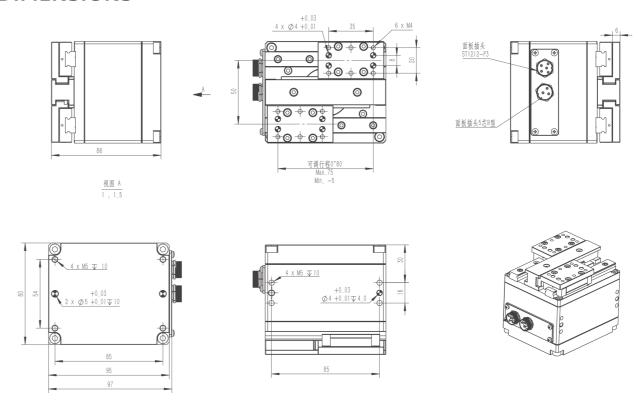
# **HEPG**80-140-1L#-C0024-P40-A

## **PRODUCT PARAMETERS**

Adjustable Stroke	0-80 mm	Rated Voltage	DC 48±10% V	
Clamping Force of One Finger	50-150 N	Maximum Current	3A	
Opening/Closing Time	0.5s		Standard :	
Positional Repeatability	±0.03 mm		Modbus RTU(RS 485 Digital I/O Optional: TCP/IP, EtherCAT, CAN, IOlink	
*Maximum Recommended Load	5Kg	Communication Protocol		
Support Drop Detection or Not	Supported			
Power-down Holding	Not Supported	International Standards Met	CE、RoHS	
Applicable Environment	5~40℃, 85% RH below	Allowable Static Load in Vertical Direction Fz	500 N	
Operating Noise	< 60 dB	Allowable Static Torque of The Slider Mx	10 N·m	
Weight	1.5 Kg	Allowable Static Torque of The Slider My	10 N·m	
IP Grade	IP40	Allowable Static Torque of The Slider Mz	10 N·m	



## **DIMENSIONS**



<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **HEPG-HP**

## **MODULAR ELECTRIC GRIPPER**

**High Precision High Rigidity** Front Mounting **Networking Applications** 



<sup>\*</sup>Fingers Need To Be Optional











B







Automotive and Related Fields



Education

## **PRODUCT ADVANTAGES**















High Precision

Installable on Five Sides

Drop Detection

Grabbing Feedback

Network Application

## **MODEL SELECTION**

Product Series	Stroke	Clamping Force	Wiring Position	Cable Fixed-end Length	Communication Mode	Power Voltage	IP Grade	Model Version ( Customer Configuration )
HEPG-HP	26	050	0	L#	C4	024	P40	Α
		1	0-side Wiring -bottom Wiring	L#-default 200mm L5000-5000mm	C0-485 C1-485+I/O(NN) C2-485+I/O(PP) C3-485+I/O(NP) C4-485+I/O(PN)	024-24V	P##	A-default B-first Upgrade -secondary Upgrade 

## **HEPG-HP**

## HEPG-HP26-050-0L#-C4024-P40-A

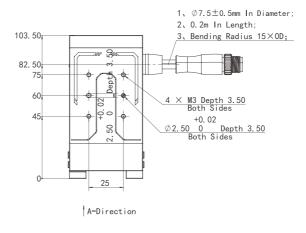
## **PRODUCT PARAMETERS**

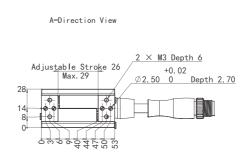
Adjustable Stroke	0-26 mm	Rated Voltage	DC 24±10% V	
Clamping Force of One Finger	5-50 N	Maximum Current	0.6 A	
Opening/Closing Time	0.35s	Rated Current	0.25 A	
Positional Repeatability	±0.02 mm		Modbus RTU(RS 485	
*Maximum Recommended Load	1 Kg	Communication Protocol	Digital I/O optional	
Support Drop Detection or Not	Supported	International Standards Met	CE、RoHS	
Applicable Environment	5~40℃, 85% RH below	Allowable Static Load in Vertical Direction Fz	200 N	
Operating Noise	< 40 dB	Allowable Static Torque of The Slider Mx	3 N·m	
Weight	0.45 Kg	Allowable Static Torque of The Slider My	2.5 N·m	
IP Grade	IP40	Allowable Static Torque of The Slider Mz	3.5 N·m	

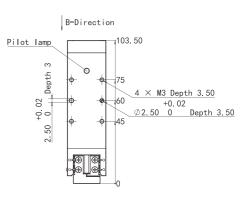


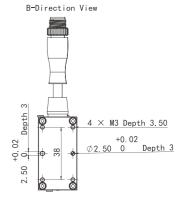
<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**











## **HEPG-M** HEPG-M06-015-0L#-D1024-P20-B

## **PRODUCT PARAMETERS**

Adjustable Stroke	6 mm	Rated Voltage	DC 24±10% V
Clamping Force of One Finger	6/15 N Two-gear adjustable	Maximum Current	0.4 A
Opening/Closing Time	0.2s	Rated Current	0.2 A
Positional Repeatability	±0.02 mm	Communication Protocol	Digital I/O
*Maximum Recommended Load	0.3 Kg	International Standards Met	CE、RoHS
Drop Detection	Supported	Allowable Static Load in Vertical Direction Fz	150 N
Applicable Environment	5~40°C, 85% RH below	Allowable Static Torque of The Slider Mx	1.2 N·m
Operating Noise	< 40 dB	Allowable Static Torque of The Slider My	1 N·m
Weight	0.20 Kg	Allowable Static Torque of The Slider Mz	0.6 N·m
IP Grade	IP20		



\*It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **PRODUCT ADVANTAGES**











Compact Size

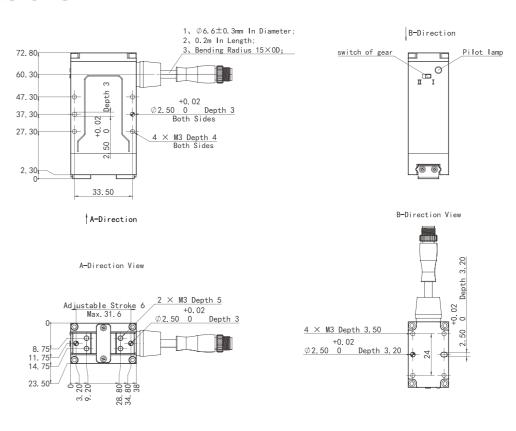
Falling Detection

Gripping Feedback Cost-effective

## **MODEL SELECTION**

Product Family	Trips	Gripping Force	Outgoing Position	Length of Fixed End of Cable	Mode of Communication	Supply n Voltage	IP Rating	Model Version ( Configured by Customers )
HEPG-M	06	015	0	L#	D1	024	P20	Α
			0-side Out 1-bottom Out	L# -200mm by Default L300-3000mm L5000-5000m	D1-I/O(NN) D2-I/O(PP) D3-I/O(NP) D4-I/O(PN)	024-24V		A-default B-initial Upgrade secondary Upgrade 

## **DIMENSIONS**



## **HEPG-L**

**LONG STROKE ELECTRIC PARALLEL GRIPPER** 

Maintenance-Free / Ultra-Large Stroke Power-down Holding / Falling Detection Position Repeatability Accuracy Industrial Protection Rrade



\*Fingers Need To Be Optional











(3)



Medical

## **PRODUCT ADVANTAGES**











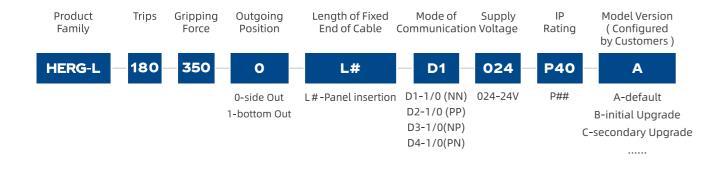






Gripping Feedback

## **MODEL SELECTION**



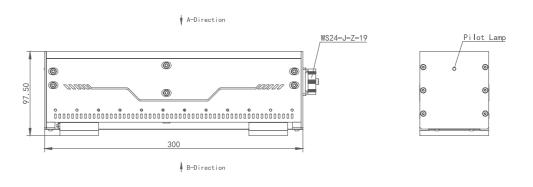
## **HEPG-L** HEPG-L180-350-0L#-D1-P40-A

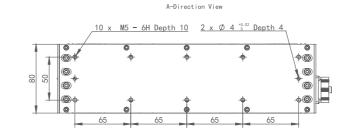
## **PRODUCT PARAMETERS**

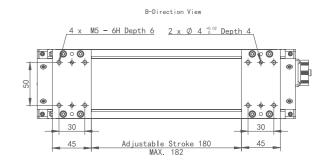
Adjustable Stroke	180 mm	Rated Voltage	DC 24±10% V
Clamping Force of One Finger	100-350 N	Maximum Current	2.8A
Opening/Closing Time	1 s	Communication Protocol	1/0
*Maximum Recommended Load	6 Kg	International Standards Met	CE、RoHS
Support Drop Detection or Not	Supported	Allowable Static Load in Vertical Direction Fz	1000 N
Applicable Environment	0~50 ℃, 85% RH below	Allowable Static Torque of The Slider Mx	76.5 N·m
Operating Noise	< 60 dB	Allowable Static Torque of The Slider My	72.5 N·m
Weight	3 kg	Allowable Static Torque of The Slider Mz	72.5 N·m
IP Grade	IP40		



## **DIMENSIONS**







<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.



## **PRODUCT ADVANTAGES**



Large Load



IP43

Protection





Collision Buffering

and Detection











Supply

024-24V

Easy Maintenance

Model Version

(Configured

by Customers )

## **MODEL SELECTION**

Product Family

HLEPG

Trips

70

Force

500

Gripping

Outgoing Position

0

0-side Out

1-bottom Out

Length of Fixed End of Cable

L5000

L#-200mm by Default

L5000-5000m

Mode of Communication Voltage

**C5** 

C0-485

C1-485+I/O(NN)

C2-485+I/O(PP)

024

Rating

A-default B-initial Upgrade C-secondary Upgrade

C3-485+I/O(NP) C4-485+I/O(PN) C5-485+I/O(NN) / 485+I/O(PN)

## **HLEPG**

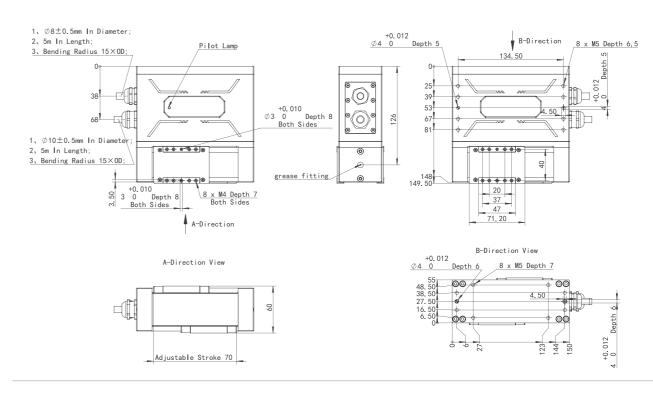
## HLEPG70-500-0L5000-C5024-P43-A

## **PRODUCT PARAMETERS**

Adjustable Stroke	0-70 mm	Body Weight	3 Kg	
Single-finger Gripping Force	40-500 N	IP Rating	IP43	
Switch On/switch Off Time	0.9s	Rated Voltage	DC 24±10% V	
Position Repeatability Accuracy	±0.02 mm	Maximum Current	2 A	
*Maximum Recommended Load	10 Kg	Rated Current	0.6 A	
Collision Buffering	Optional	Communication	Modbus RTU(RS 485	
Collision Detection	Support detection in X/Y/Z direction	Protocol	Digital I/O	
Falling Detection	Supported	Compliance With International Standard	CE、RoHS	
Power-down Holding	Supported	Allowable Static Load in Vertical Direction Fz	1000 N	
Power-off Protection	Supported	Allowable Static Torque of The Slider Mx	200 N·m	
Service Environment	5~40°C,85% RH below	Allowable Static Torque of The Slider My	150 N·m	
Operating Noise	<60 dB	Allowable Static Torque of The Slider Mz	150 N·m	



## **DIMENSIONS**



<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.



## **ELECTRIC ROTARY GRIPPER**

Force, Position and Rotation Angle Adjustable and Controllable Forward and Reverse Infinite Rotation Drive and Control-integrated **Networking Application** 

\*Fingers Need To Be Optional













H





## **PRODUCT ADVANTAGES**



Precise Force

Control



IP40 Protection

Grade







Clamping

Rotation In One





Drop

Detection

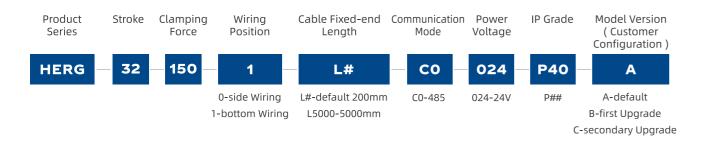




Ultra-thin

Network Application

## **MODEL SELECTION**



## **HERG** HERG08-023-1L#-C0024-P40-A

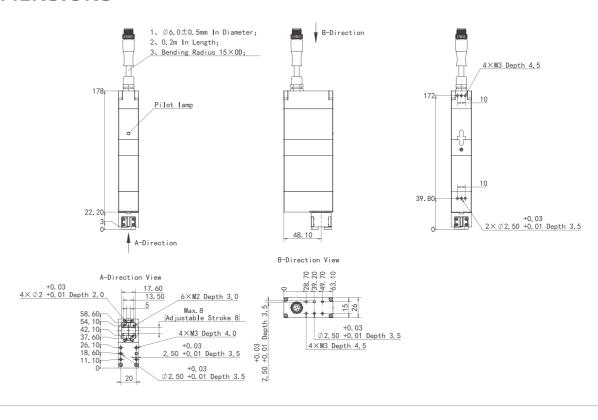
## **PRODUCT PARAMETERS**

Adjustable Stroke	0-8 mm	Operating Noise	< 70 dB	
Clamping Force of One Finger	4-23 N	Weight	0.6 Kg	
Opening/Closing Time	0.15s	IP Grade	IP40	
Peak Torque	0.3 N·m	Rated Voltage	DC 24±10% V	
Rated Torque	0.12 N·m	Maximum Current	2 A	
Rotation Angle	Infinite rotation	Rated Current	0.4 A	
Maximum Rotational Speed	1500°/s	Communication Protocol	Modbus RTU(RS 485)	
Maximum Allowable Inertia	100 kgmm²	International Standards Met	CE、RoHS	
Clamping Repeatability	±0.02 mm	Allowable Static Load in Vertical Direction Fz	100 N	
Rotation Repeatability	±0.5°	Allowable Static Torque of The Slider Mx	1.5 N·m	
*Maximum Recommended Load	0.3 Kg	Allowable Static Torque of The Slider My	1.5 N·m	
Drop Detection	Supported	Allowable Static Torque of The Slider Mz	1.5 N·m	
Applicable Environment	5~40°C, 85% RH below			



\*It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**



# HERG32-150-1L#-C0024-P40-A

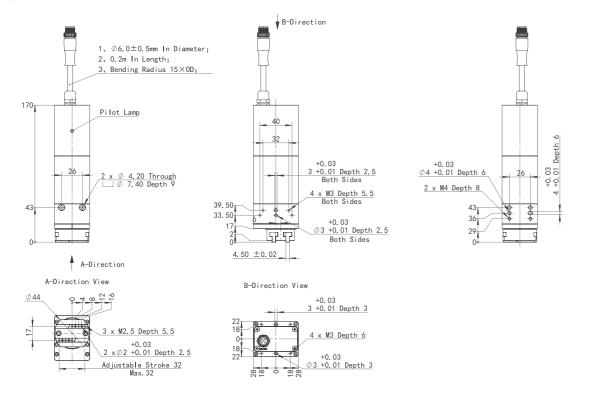
## **PRODUCT PARAMETERS**



Adjustable Stroke	0-32 mm	Operating Noise	< 70 dB	
Clamping Force of One Finger	40-100 N	Weight	0.7 Kg	
Opening/Closing Time	0.5s	IP Grade	IP40	
Peak Torque	1 N·m	Rated Voltage	DC 24±10% V	
Rated Torque	0.2 N·m	Maximum Current	4 A	
Rotation Angle	Infinite rotation	Rated Current	0.5 A	
Maximum Rotational Speed	1500°/s	Communication Protocol	Modbus RTU(RS 485)	
Maximum Allowable Inertia	200 kgmm²	International Standards Met	CE、RoHS	
Clamping Repeatability	±0.02 mm	Allowable Static Load in Vertical Direction Fz	200 N	
Rotation Repeatability	±0.5°	Allowable Static Torque of The Slider Mx	2 N·m	
Maximum Recommended Load	0.5 Kg	Allowable Static Torque of The Slider My	2 N·m	
Drop Detection	Supported	Allowable Static Torque of The Slider Mz	2 N·m	
Applicable Environment	5~40°C, 85% RH below			

<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**



# **HERG**HERG32-150T-1L#-C0024-P40-A

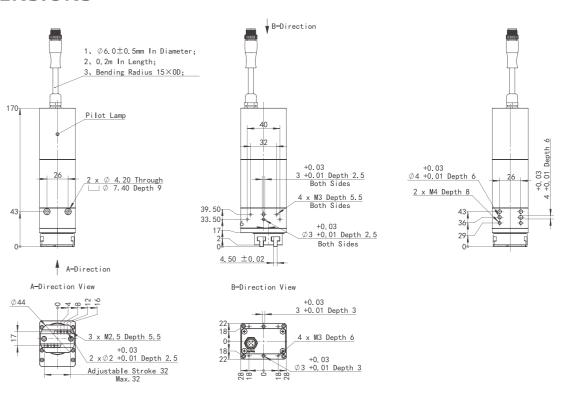
## **PRODUCT PARAMETERS**

Adjustable Stroke	0-32 mm	Operating Noise	4 70 dD	
Adjustable Stroke	0-32 111111	Operating Noise	< 70 dB	
Clamping Force of One Finger	40-100 N	Weight	0.7 Kg	
Opening/Closing Time	0.5s	IP Grade	IP40	
Peak Torque	1.5 N·m	Rated Voltage	DC 24±10% V	
Rated Torque	0.3 N·m	Maximum Current	4 A	
Rotation Angle	Infinite rotation	Rated Current	0.6 A	
Maximum Rotational Speed	1000°/s	Communication Protocol	Modbus RTU(RS 485)	
Maximum Allowable Inertia	200 kgmm²	International Standards Met	CE、RoHS	
Clamping Repeatability	±0.02 mm	Allowable Static Load in Vertical Direction Fz	200 N	
Rotation Repeatability	±0.5°	Allowable Static Torque of The Slider Mx	2 N·m	
Maximum Recommended Load	0.5 Kg	Allowable Static Torque of The Slider My	2 N·m	
Drop Detection	Supported	Allowable Static Torque of The Slider Mz	2 N·m	
Applicable Environment	5~40°C, 85% RH below			



<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**



## **IHERG**

## LIGHTWEIGHT ELECTRIC **ROTARY GRIPPER**

Stroke 8mm Strong Compatibility High Integration Compact Size

\*Fingers Need To Be Optional

















H) Homwing

Medical

## Others

## **PRODUCT ADVANTAGES**













Ultra-thin and Small Volume

Integrated Drive and Control

High Integration

Drop Detection

Cable Fixed-end Communication Power

Centripetal Limbs Free Self-assembly

Power Down Hold

Model Version

(Customer Configuration)

## **MODEL SELECTION**

Product Series

**IHERG** 

08

Stroke Clamping Force

015

Wiring Position

Length L#

**C1** 

C0-485

Mode

024 024-24V

Voltage

P40

IP Grade

A-default B-first Upgrade C-secondary Upgrade

0-side Wiring 1-bottom Wiring

L#- Panel Insertion Navigation

C1-485+1/O (NN) C2-485+1/O(PP) C3-485+1/0 (NP) C4-485+1/O(PN) A1-CAN2.0A+1/O(NN)

A2-CAN2.0A+1/O(PP)

**IHERG** 

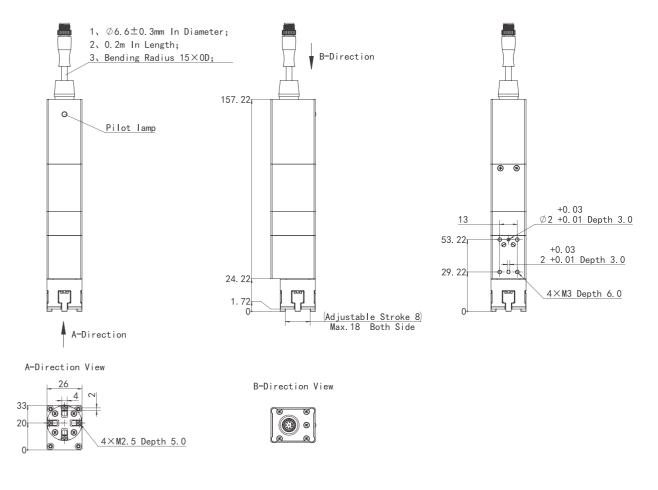
## IHERG08-015-1L#-C1024-P40-A

## **PRODUCT PARAMETERS**

Gripping Force Range	10-15N	Rotational Position Accuracy	±0.5°
Total Travel	8mm	Rotation Status Feedback	have
Opening and Closing Positioning Accuracy	±0.2mm	Rated Current	0.5A
Feedback On Clamping Status	have	Maximum Current	1A (subject to actual)
Opening and Closing Time	0.3s	Communication Protocol	RS485、I/O、Can
Maximum Rotational Speed	1500°/s	Applicable Environment	5~40°C,85% RH below
Rotational Torque Rating	0.05N.m	IP Grade	IP40
Rotational Peak Torque	0.2Nm	Operating Noise	<50dB



## **DIMENSIONS**



## **IHERG**

## IHERG16-030-1L#-C1024-P40-A01

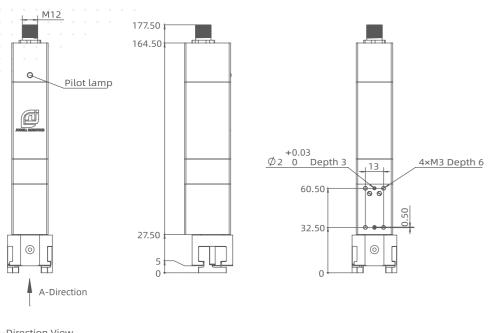


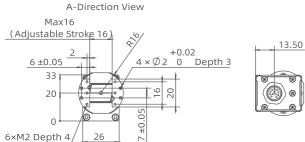
## 产品参数

Total Travel	16mm	Operating Noise	< 70dB	
Gripping Force Range	40-70 N	Weight	0.31kg	
Opening and Closing Time	0.7s	IP Grade	IP40	
Rotational Position Accuracy	1.2°	Rated Voltage	24V	
*Maximum Recommended Load	0.2kg	Maximum Current	1.5A	
Falling Detection	Support	Rated Current	0.15A	
Power-down Holding	Support	Communication	MODBUS RTU(RS485)	
Applicable Environment	5~40℃, 85% RH below	- Communication Protocol	DIGITAL I/O	

<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**





















Ultra-Large Stroke

Precise Force Control

IP65 Protection Grade

Drop Detection

Gripping Feedback

Power Down Hold

## **MODEL SELECTION**

Product Series

HRG

52

Stroke Clamping

050

Wiring Position Cable Fixed-end Communication Power Length

Voltage

024

Model Version (Customer Configuration)

0-side Wiring

L#-默认200mm

C0-485 1-bottom Wiring L5000-5000mm C1-485+1/O (NN)

> C2-485+1/O(PP) C3-485+1/0 (NP) C4-485+1/O(PN)

**C3** 

A-default B-first Upgrade C-secondary Upgrade

## HRG HRG52-050-0L#-C3024-P54-A

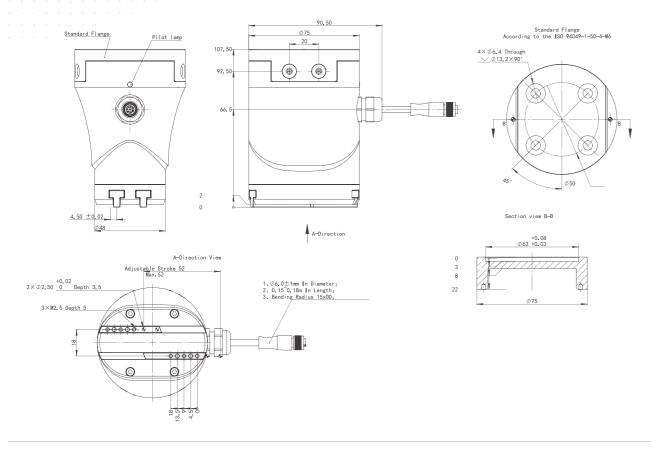
## **PRODUCT PARAMETERS**



Adjustable Stroke	0-52 mm	IP Grade	IP54
Clamping Force of One Finger	2-50 N	Rated Voltage	DC 24±10% V
Opening/Closing Time	0.65 s	Maximum Current	0.8 A
Position Repeatability Accuracy	±0.02 mm	Rated Current	0.5A
*Maximum Recommended Load	1 Kg	Communication Protocol	Modbus RTU (RS 485) Digital I/0
Support Drop Detection or Not	Supported	International Standards Met	CE、RoHS
Power-down Holding	Supported	Allowable Static Load in Vertical Direction Fz	1000 N
Applicable Environment	5~40 ℃ , 85% RH below	Allowable Static Torque of The Slider Mx	76.5 N·m
Operating Noise	< 40 dB	Allowable Static Torque of The Slider My	72.5 N·m
Weight	0.75 Kg	Allowable Static Torque of The Slider Mz	72.5 N·m

<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**



## **HRG** HRG75-300-0L#-C0024-P65-A

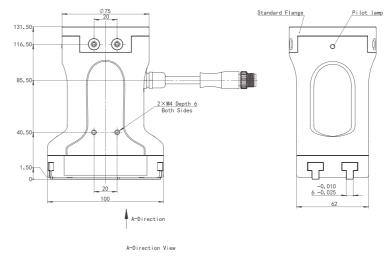
## **PRODUCT PARAMETERS**

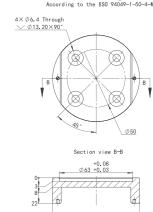
Adjustable Stroke	0-75 mm	IP Grade	IP65
Clamping Force of One Finger	40-300 N	Rated Voltage	DC 24±10% V
Opening/Closing Time	0.55 s	Maximum Current	1.5 A
Position Repeatability Accuracy	±0.02 mm	Rated Current	0.55 A
*Maximum Recommended Load	6 Kg	Communication Protocol	MODBUS RTU(RS 485)
Support Drop Detection or Not	Supported	International Standards Met	CE、RoHS
Power-down Holding	Supported	Allowable Static Load in Vertical Direction Fz	400 N
Applicable Environment	5~40 ℃ , 85% RH below	Allowable Static Torque of The Slider Mx	8 N·m
Operating Noise	< 40 dB	Allowable Static Torque of The Slider My	8 N·m
Weight	1.5 Kg	Allowable Static Torque of The Slider Mz	8 N·m

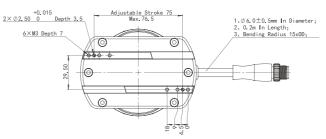


<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**







## **HRCG**

## **ROTARY RADIAL GRIPPER**

Three-Finger Radial Grabbing Large Stroke Suitable For Objects With Different Diameters









Manufacturing



Electric Appliance

(4)



Medical Device



Education

## **PRODUCT ADVANTAGES**









Length









**Model Version** 

( Customer

Configuration)

## **MODEL SELECTION**

Product Series **HRCG** 

Stroke Clamping Force

065



Wiring

Position



CO

Mode



Voltage

B-first Upgrade C-secondary Upgrade

## HRCG90-065

## RCG90-065-0L#-C0024-P40-A

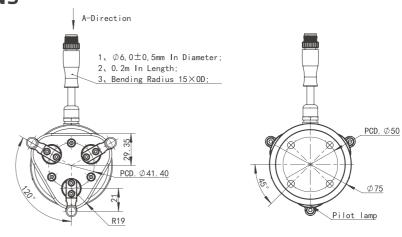
## **PRODUCT PARAMETERS**

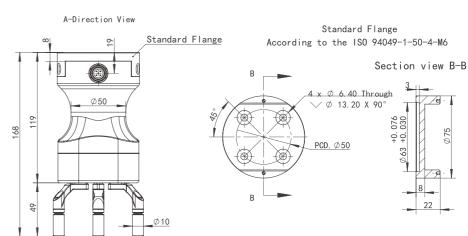
Adjustable Stroke	65N	Weight	1Kg
Recommended maximum clamping diameter	90mm	IP Grade	IP40
Position Repeatability Accuracy	±0.02 mm	Rated Voltage	DC 24±10 V
*Maximum Recommended Load	2 kg	Maximum Current	1.5 A
Power-down Holding	Supported	Rated Current	0.45 A
Applicable Environment	5-40℃, 85% RH below	International Standards Met	CE、RoHS
Operating Noise	< 40 dB	Communication Protocol	Modbus RTU(RS485)



<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**





C0-485 024-24V A-default 0-side Wiring L#-默认200mm L5000-5000mm

Cable Fixed-end Communication Power

**33** en.homwing.com



# **HEVS**HEVS01-1L#-C1024-P40-A

## **PRODUCT PARAMETERS**

Vacuum Degree	10%-60%	Operating Noise	<70dB	
Maximum Flow	2.5 L/min	Rated Voltage	DC 24±10% V	
Body Weight	0.3kg Rated Current		0.13 A	
*Maximum Recommended Load	1kg	Peak Current	0.3 A	
Fastest Adsorption Time	0.1s	Compliance With International Standards	CE、RoHS	
Fastest Release Time	0.1s	Communication	Modbus RTU(RS485)	
Degree of Protection	IP40	Protocol	Digital I/O	
Service Environment	0~40°C, 85% RH below			



\*It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **PRODUCT ADVANTAGES**









IP40 Protection Level

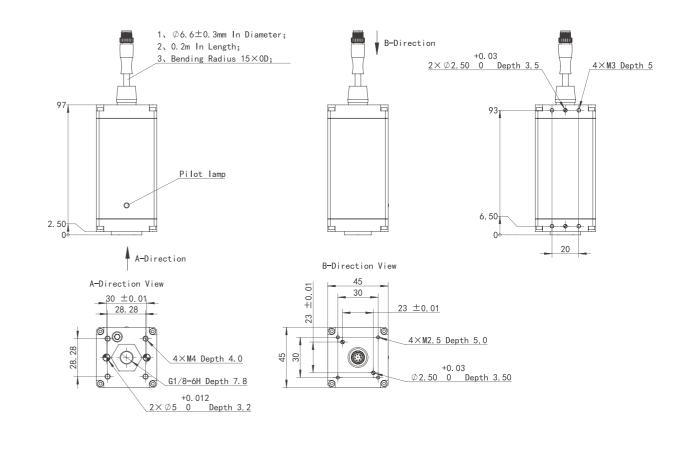
Drop Detection

Grabbing Feedback Power-off Protection

## **MODEL SELECTION**

Product Series	Load	Wiring Position	Cable Fixed-end Length	Communication Mode	Power Voltage	IP Grade	Model Version ( Customer Configuration )
HEVS	08	<b>o</b>	L#	C1 —	024	P40	<b>—</b> A
		0-side Wiring	L#-default 200mm L5000-5000mm	C0-485 C1-485+I/O(NN) C2-485+I/O(PP) C3-485+I/O(NP) C4-485+I/O(PN)	024-24V		A-default B-first Upgrade C-secondary Upgrade 

## **DIMENSIONS**



## **HEVS**HEVS08-0L#-C1024-P54-A

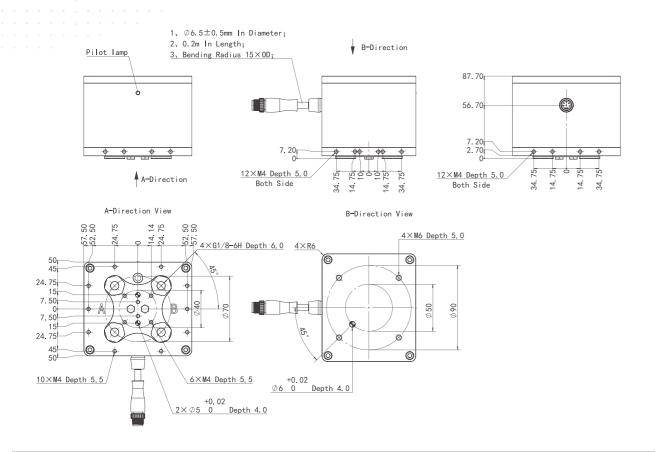
## PRODUCT PARAMETERS



Vacuum Degree	10%-70%	Operating Noise	<70dB	
Maximum Flow	10 L/min	Rated Voltage	DC 24±10% V	
Body Weight	1.4kg	Rated Current	0.5 A	
*Maximum Recommended Load	8kg	Peak Current	3.8 A	
Fastest Adsorption Time	0.4s	Compliance With International Standards	CE、RoHS	
Fastest Release Time	0.2s	Communication	Modbus RTU(RS485) Digital I/O	
Degree Of Protection	IP54	Protocol		
Service Environment	0~40℃, 85% RH below			

<sup>\*</sup>It depends on the shape of the object to be grabbed and the friction of the contact surface. The center of gravity of the object to be grabbed will affect the load. If you have any question, please feel free to contact us.

## **DIMENSIONS**



## HLRA

# LINEAR ROTARY ACTUATOR

"L+R " Dual Axis Integration
Micron-level High Precision Positioning
Precision Force-controlled Soft Landing
Highly-efficient, Compact and Light-weight













Precision Manufacturing



Electrical Appliance



Lithium Cell



Semiconductor

## **PRODUCT ADVANTAGES**



#### **PRECISION**

The accuracy deviation of force control is ±3g when the linear motor is repeatedly positioned to the same point by the motion control algorithm in the straight zone 3



#### **PRECISE**

The linear precision optical encoder realizes micron-level resolution, and the 17-bit encoder is rotated to accurately locate the position of each component in the pick-and-place process to avoid the problem of position offset or overlap.



#### **ULTRA-THIN SIZE**

"L+R" highly integrated Simplified structure, simple maintenance



### **SOFT LANDING**

The precision force-controlled soft landing function realizes the intelligent pick-and-place of flexible contact, efficiently completes chip packaging, mounting and other processes, and improves the product yield through flexible operation.



#### **TEST**

Due to its high-speed and high-precision force control output characteristics, it is also widely used in durability and sensitivity tests of multi-function switches, keys, keyboards, touch panels, etc.



#### **LINEAR ROTATION**

High-speed pick-and-place movement, providing accurate linear and rotary actions, instantaneous reading, analysis, and feedback of force and position data before adjustment.

## HLRA HLRA15-20/25-20/40-20

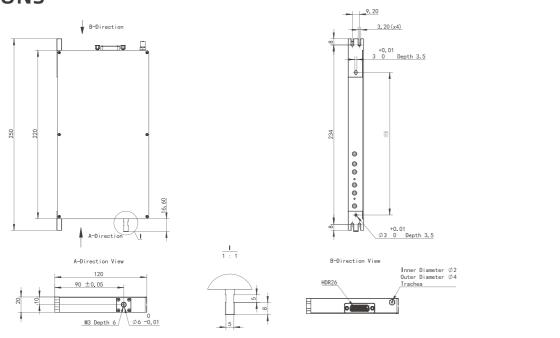
## **PRODUCT PARAMETERS**



Parameter Category	Model No.	HLRA15-20	HLRA25-20	HLRA40-20
L-axis	Adjustable Stroke	15mm	25mm	40mm
	Rated Thrust	10N	10N	10N
	Peak Thrust N	35N	35N	35N
	Thrust Constant	11.4 N/A	11.4 N/A	11.4 N/A
	Rated Current	0.87A	0.87A	0.87A
	Peak Current	3.1A	3.1A	3.1A
	Linear Encoder Resolution	0.2µm	0.2µm	0.2µm
	Position Repeat Positioning Accuracy	±1um	±1um	±1um
Force Control Accuracy	20~50g	±3g	±3g	±3g
	50~200g	±10g	±10g	±10g
R-axis	Rotary Stroke	±180°	±180°	±180°
	Rotary Encoder Resolution	17 bits	17 bits	17 bits
	Rotational Positioning Accuracy	±0.02°	±0.02°	±0.02°
	Rated Torque	0.01 N·m	0.01 N·m	0.01 N·m
	Peak Torque	0.043 N·m	0.043 N·m	0.043 N·m
	Rated Current	0.34A	0.34A	0.34A
	Peak Current	1.2A	1.2A	1.2A
	Radial Runout	±5µ	±5µ	±5µ
Ontology Parameters	Voltage	DC 24±10%	DC 24±10%	DC 24±10%
	Service Environment	5-40°	4A	4A
	Body Weight	0.60 Kg	0.80 Kg	1.00 Kg

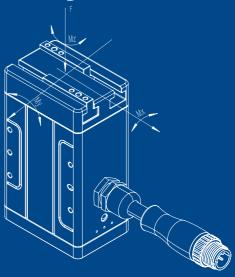
## **DIMENSIONS**

\*The size diagram is HLRA40-20

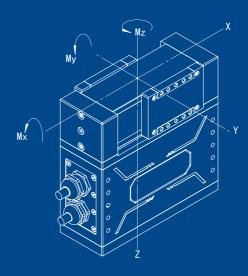


## **TORQUE DIAGRAM**

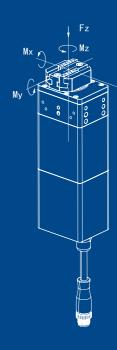
## **HEPG Series Torque Diagram**



## **HLEPG Series Torque** Diagram



## **HERG Series Torque** Diagram



# PRODUCT APPLICATION EXAMPLE

## Medical automation equipment

The micro drive control integrated electric gripper and rotation-clamping-integrated electric servo gripper independently developed by Homwing for the in-vitro diagnosis and laboratory automation equipment have been applied in several testing automation equipment. The compact and integrated structure can greatly simplify the tedious integrated design of previous clamping device. Functions such as drop detection, grabbing feedback and self-lock under power failure make the equipment more intelligent.

## Lithium battery automation equipment

There are several scenarios requiring the loading and unloading by robots in the PACK production process of power battery. Homwing has developed heavy-duty modular electric gripper for this scenario which boasts adjustable and controllable torque, speed and position and the outstanding performances including self-lock under power failure, ultra-large stroke, drop detection and grabbing feedback. Meanwhile, the design of installable on three sides provides better suitability.

## 3 3C spare part assembly and testing

In 3C field with extremely high appearance requirements for parts clamping, Homwing has designed and developed electric grippers more suitable for irregular parts, which own the functions and characteristics of high frequency and high precision, making the clamping of spare parts in 3C field more easier.

## Packaging automation equipment

In the packaging fields such as food packaging and medicine packaging, due to the need of maintaining the intact packaging, there is an accurate force control requirement for the clamping equipment. In the frequent usage scenarios, the clamping function is required to be stable. Therefore, Homwing's modular electric gripper can perfectly meet the clamping requirement in the packaging industry and provide excellent solutions for the industry.

## OUR SERVICES

## We are not only a product supplier but also your service expert.

We are committed to providing you with comprehensive and product & marketoriented services in the life cycle of each product and make continuous improvement and optimization based on your opinions.



## Offline service+ online service

Please call our hotline or visit our company to obtain the required product materials or services. If necessary, our experienced service personnel are also willing to provide on-site expert consultation and service.

You can also follow our social media account to learn more about the products and services.









O

Tik Tok



## **Service contract**

We provide corresponding service contracts for you to ensure that we can provide technical support for you in case of any failure, thus facilitating you to make long-term plans for the product.



## **Spare parts**

We understand all spare parts required for the products and will provide you with cost-effective and high-quality spare parts based on professional consultation.



